# **Reality Modeling for Transportation Projects**

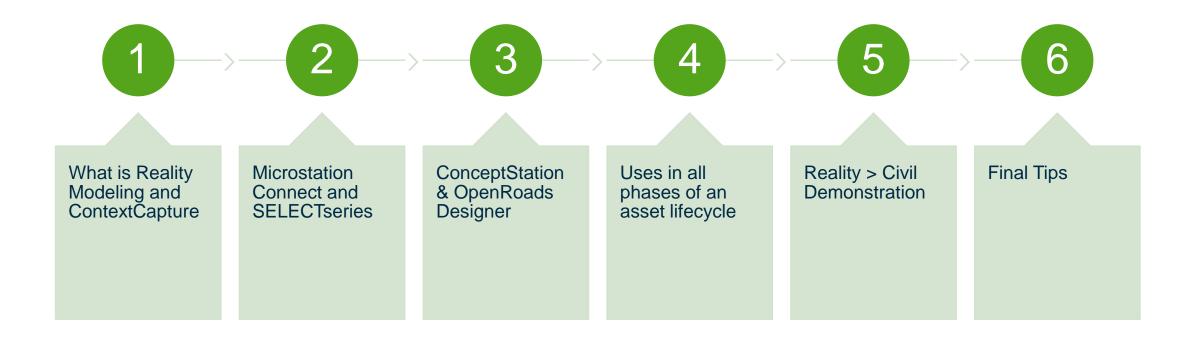
**Robert Nice – Bentley Systems** 





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### **Reality Modeling and Bentley Civil Design Software**



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### **Reality Modeling**

Capturing existing conditions in **3D using one or a combination of devices** (UAVs, Handheld Camera, Laser Scanner) to support different applications such as **Mapping**, **Design, Construction, Inspection** and **Asset Management** 



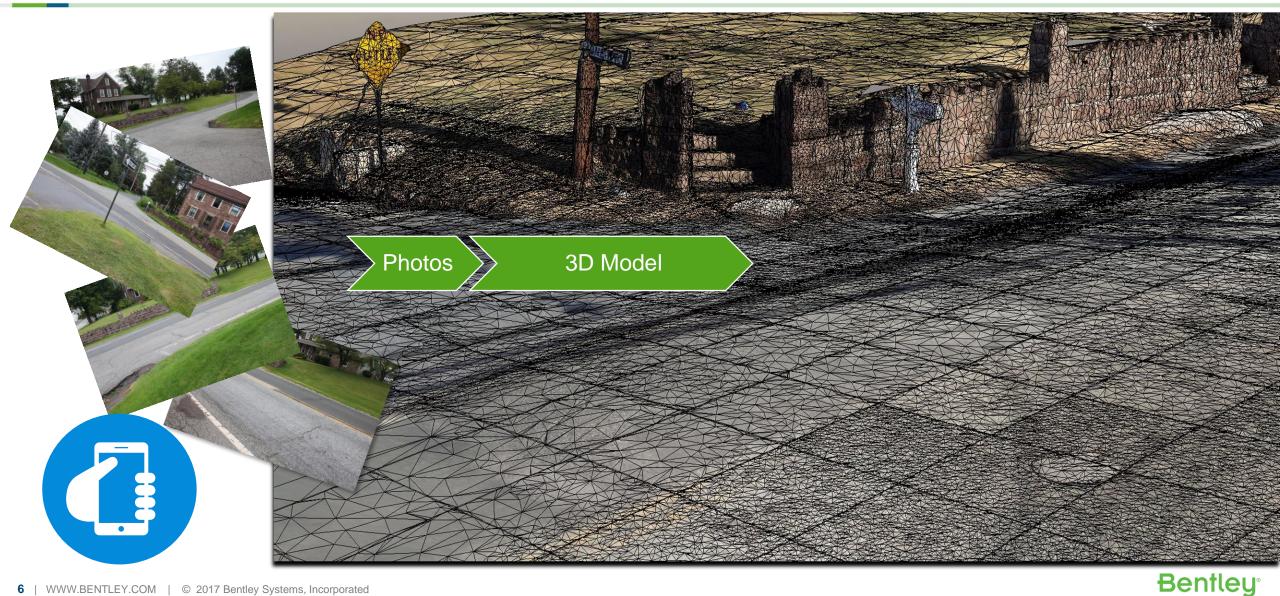








### **Scalable3D Models - Handheld Camera**



### **Site Models – Drone w/ Camera**

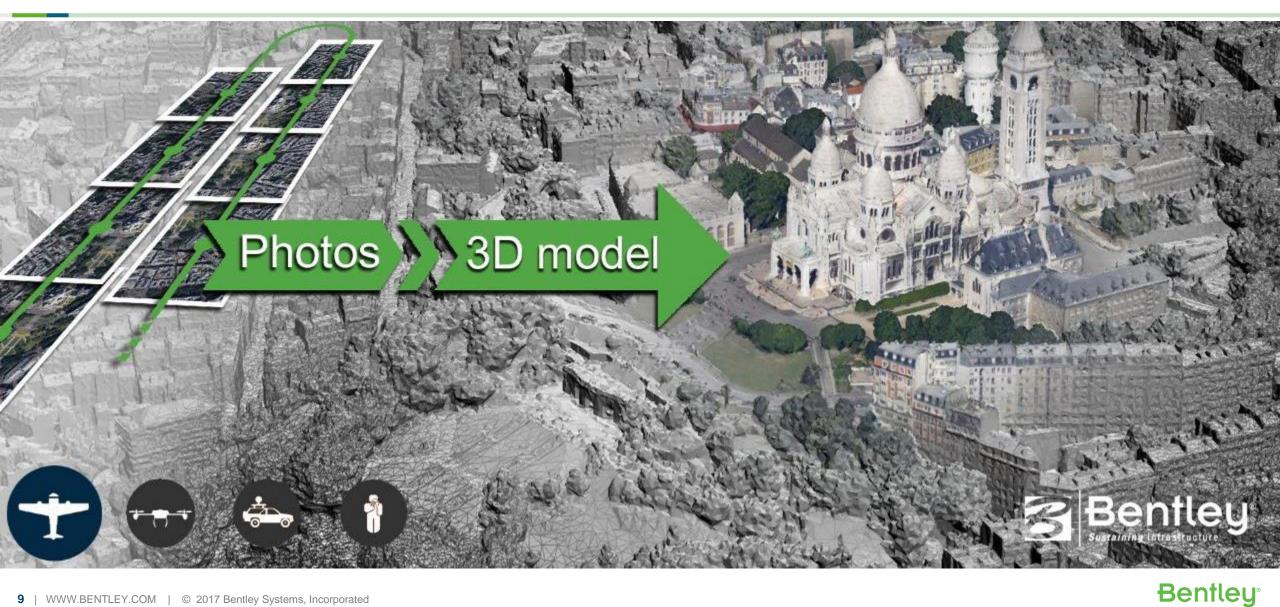


### Linear Models - Vehicle w/ Camera

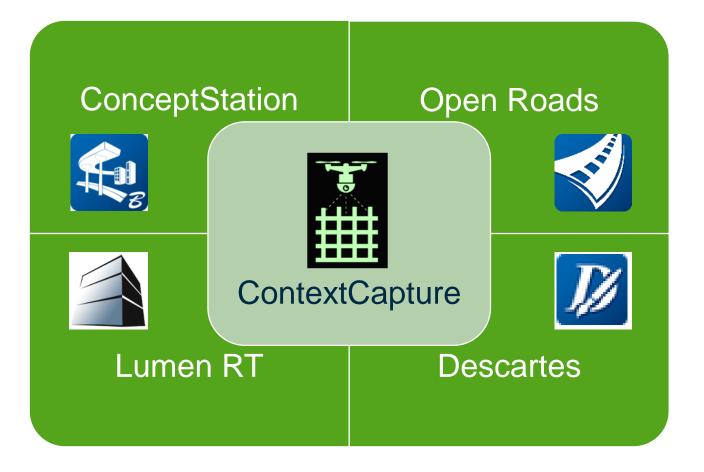




# ...to a whole city!



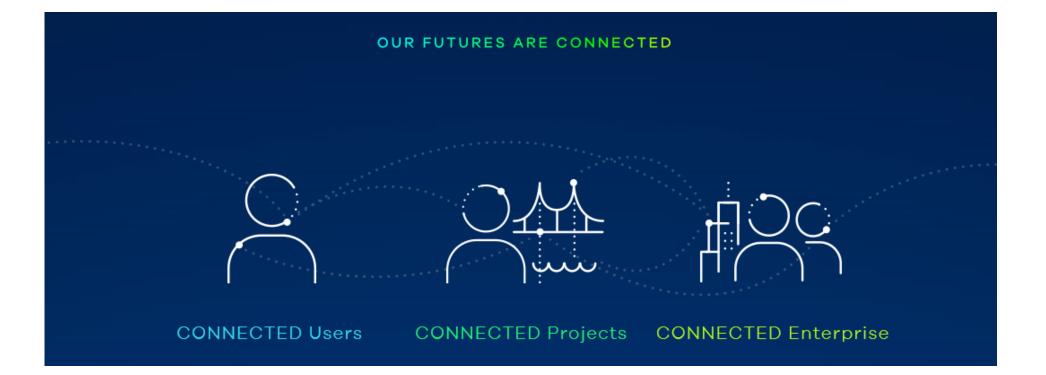






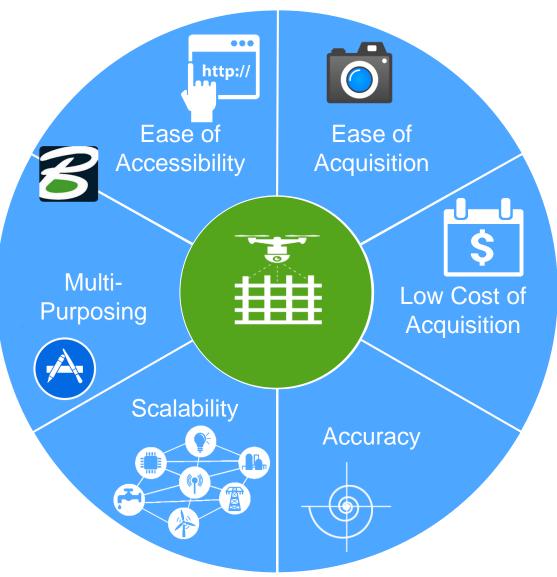




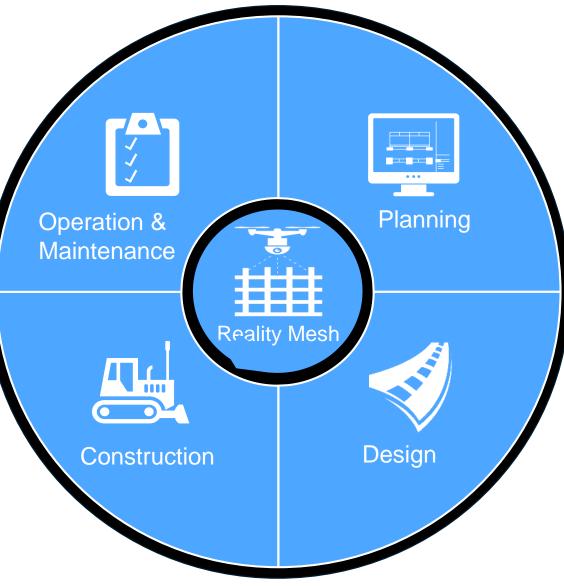


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OpenRoads ConceptStation CONNECT Edition

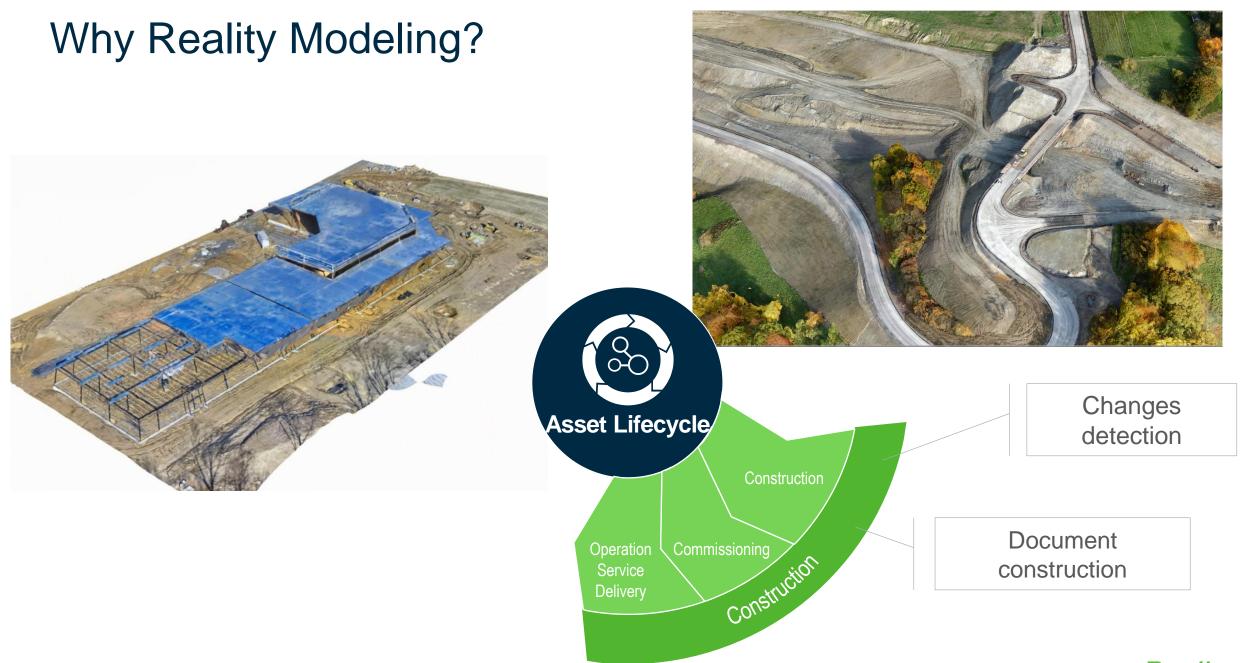
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# Why Reality Modeling?



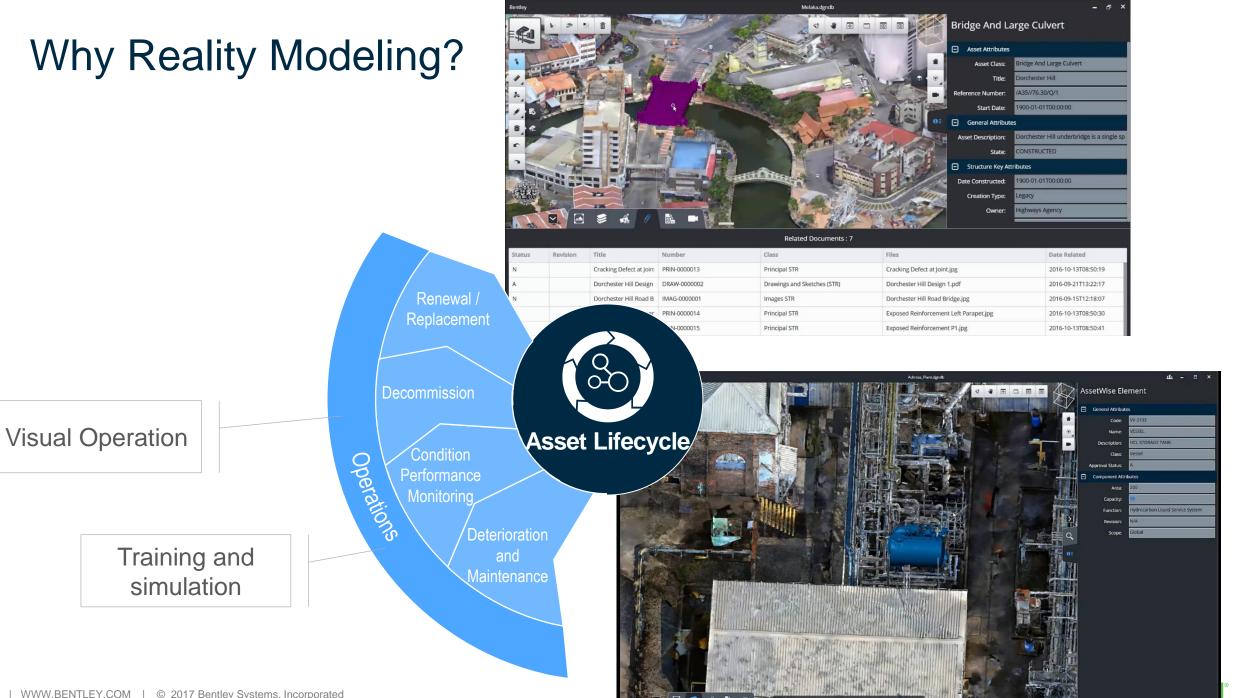


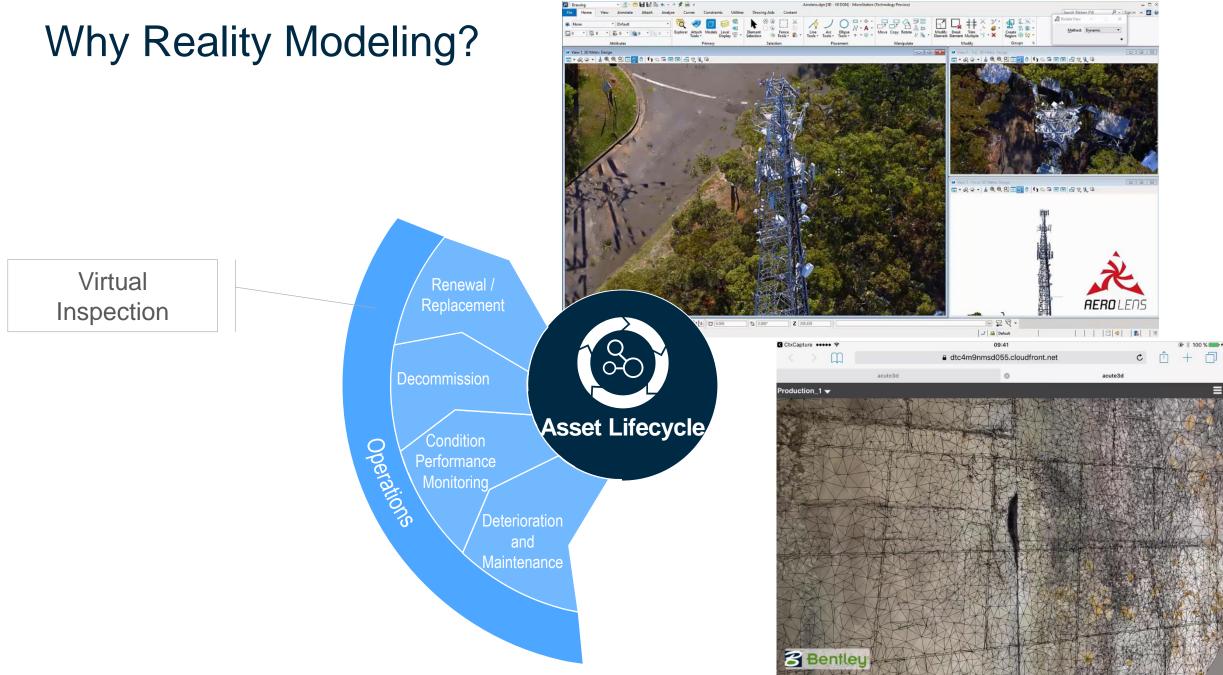
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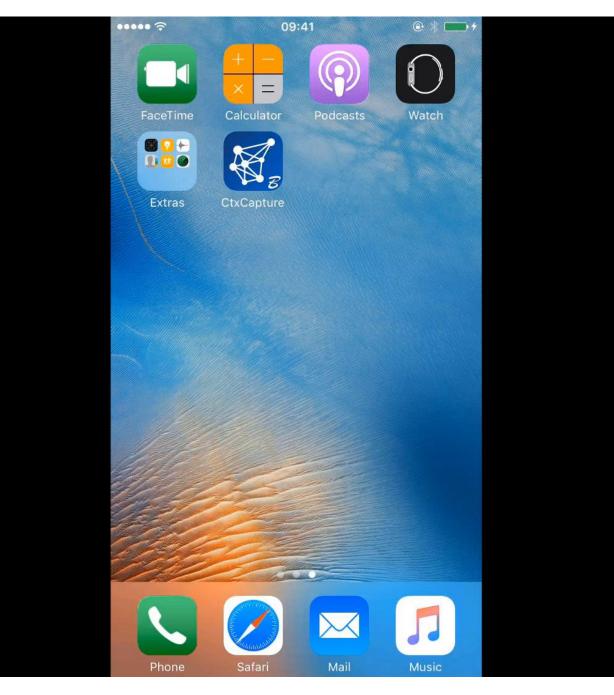
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# Why Reality Modeling?









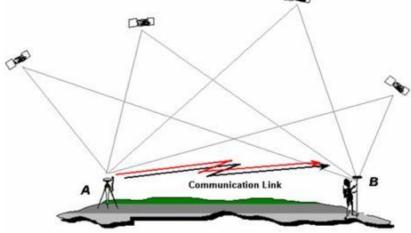
## Accuracy and Precision

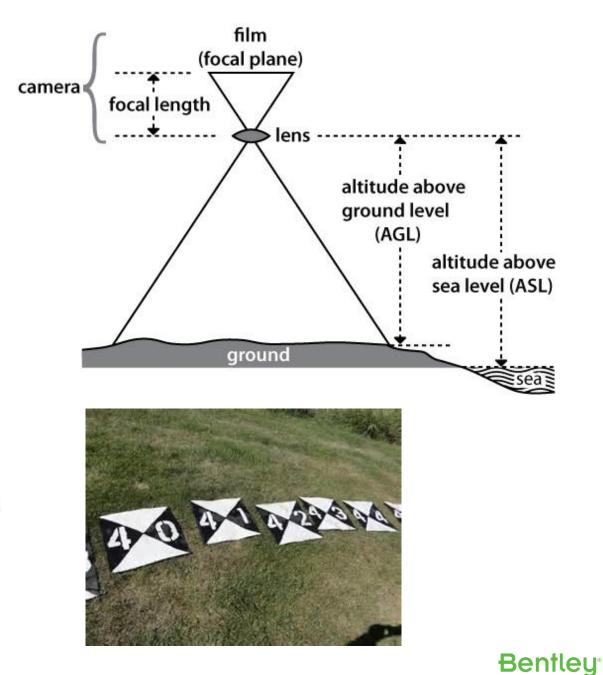
- Spatial Accuracy
  - Measurement of How close a Point or position comes to a true value
- Precision / Scale
  - Measure of how close a series of measurements are to one another



# Accuracy and Precision

- Direct relation to image resolution and number of angles viewing the scene
- 2X Pixel resolution
- GPS allows for a high degree of accuracy and scale
- Highest spatial accuracy achieved through ground control
- Deviation between laser and photos is typically within the error ranges of the different sensors (given adequate pixel resolution







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